## Machine Learning with Quantum-Inspired Tensor Networks


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## Collaboration with David J. Schwab, Northwestern and CUNY Graduate Center



Quantum Machine Learning, Perimeter Institute, Aug 2016

## Exciting time for machine learning



Medicine


Self-driving cars


Materials Science / Chemistry

## Progress in neural networks and deep learning


neural network diagram

## Convolutional neural network


"MERA" tensor network


Are tensor networks useful for machine learning?

## This Talk

Tensor networks fit naturally into kernel learning (Also very strong connections to graphical models)

Many benefits for learning

- Linear scaling
- Adaptive
- Feature sharing


## Machine Learning



Neural Nets


Kernel Learning


Supervised Learning


Boltzmann Machines


Quantum Monte Carlo




Tensor Networks

Machine Learning


Supervised Learning

Physics


## What are Tensor Networks?

How do tensor networks arise in physics?

Quantum systems governed by
Schrödinger equation:

$$
\hat{H} \vec{\Psi}=E \vec{\Psi}
$$

It is just an eigenvalue problem.

The problem is that $\hat{H}$ is a $2^{\mathrm{N}} \times 2^{\mathrm{N}}$ matrix
$\Longrightarrow$ wavefunction $\vec{\Psi}$ has $2^{\mathrm{N}}$ components


$$
=E \cdot \begin{array}{r} 
\\
\\
\\
\exists \exists \\
\\
\\
\\
\\
\\
\exists \exists
\end{array}
$$

Natural to view wavefunction as order-N tensor

$$
|\Psi\rangle=\sum_{r} \Psi^{s_{1} s_{2} s_{3} \cdots s_{N}}\left|s_{1} s_{2} s_{3} \cdots s_{N}\right\rangle
$$

Natural to view wavefunction as order- N tensor


## Tensor components related to probabilities of e.g. Ising model spin configurations



## Tensor components related to probabilities of e.g. Ising model spin configurations



Must find an approximation to this exponential problem


Simplest approximation (mean field / rank-1)
Let spins "do their own thing"

$$
\Psi^{s_{1} s_{2} s_{3} s_{4} s_{5} s_{6}} \simeq \psi^{s_{1}} \psi^{s_{2}} \psi^{s_{3}} \psi^{s_{4}} \psi^{s_{5}} \psi^{s_{6}}
$$



Expected values of individual spins ok
No correlations

Restore correlations locally

$$
\Psi^{s_{1} s_{2} s_{3} s_{4} s_{5} s_{6}} \simeq \psi^{s_{1}} \psi^{s_{2}} \psi^{s_{3}} \psi^{s_{4}} \psi^{s_{5}} \psi^{s_{6}}
$$



Restore correlations locally

$$
\begin{aligned}
\Psi^{s_{1} s_{2} s_{3} s_{4} s_{5} s_{6}} \simeq & \psi_{i_{1}}^{s_{1}} \psi_{i 1}^{s_{2}}
\end{aligned} \psi^{s_{3}} \psi^{s_{4}} \psi^{s_{5}} \psi^{s_{6}}
$$

Restore correlations locally

$$
\Psi^{s_{1} s_{2} s_{3} s_{4} s_{5} s_{6}} \simeq \psi^{s_{1}} \psi_{i_{1} i_{2}}^{s_{2}} \psi_{i_{2} i_{3}}^{s_{3}} \psi_{i_{3} i_{4}}^{s_{4}} \psi^{s_{4}} i^{i_{5}} \psi_{i_{5}}^{s_{6}}
$$

matrix product state (MPS)
Local expected values accurate
Correlations decay with spatial distance

"Matrix product state" because
retrieving an element $=$ product of matrices

"Matrix product state" because
retrieving an element $=$ product of matrices

## Tensor diagrams have rigorous meaning



Joining lines implies contraction, can omit names

$\longleftrightarrow$

$$
A_{i j} \underbrace{}_{j k}=A B
$$




MPS approximation controlled by bond dimension "m" (like SVD rank)

Compress $2^{N}$ parameters into $N \cdot 2 \cdot m^{2}$ parameters
$m \sim 2^{\frac{N}{2}}$ can represent any tensor

## Friendly neighborhood of "quantum state space"



## MPS lead to powerful optimization techniques (DMRG algorithm)



White, PRL 69, 2863 (1992)
Stoudenmire, White, PRB 87, 155137 (2013)

## Besides MPS, other successful tensor are PEPS and MERA



PEPS
(2D systems)


MERA
(critical systems)

Evenbly, Vidal, PRB 79, 144108 (2009)
Verstraete, Cirac, cond-mat/0407066 (2004)
Orus, Ann. Phys. 349, 117 (2014)

## Supervised Kernel Learning

## Supervised Learning

Very common task:

Labeled training data (= supervised)

Find decision function $f(\mathbf{x})$

$$
\begin{array}{ll}
f(\mathbf{x})>0 & \mathrm{x} \in A \\
f(\mathrm{x})<0 & \mathrm{x} \in B
\end{array}
$$

Input vector x e.g. image pixels

## ML Overview

Use training data to build model


## ML Overview

Use training data to build model


## ML Overview

Use training data to build model


Generalize to unseen test data

## ML Overview

Popular approaches

Neural Networks

$$
f(\mathbf{x})=\Phi_{2}\left(M_{2} \Phi_{1}\left(M_{1} \mathbf{x}\right)\right)
$$



Non-Linear Kernel Learning

$$
f(\mathbf{x})=W \cdot \Phi(\mathbf{x})
$$



## Non-linear kernel learning

Want $f(\mathbf{x})$ to separate classes


Linear classifier

$$
f(\mathbf{x})=W \cdot \mathbf{x}
$$

often insufficient


## Non-linear kernel learning

Apply non-linear "feature map" $\mathrm{x} \rightarrow \Phi(\mathrm{x})$


## Non-linear kernel learning

Apply non-linear "feature map" $\mathrm{x} \rightarrow \Phi(\mathrm{x})$


Decision function

$$
f(\mathbf{x})=W \cdot \Phi(\mathbf{x})
$$

## Non-linear kernel learning



> | Decision function | $f(\mathbf{x})=W \cdot \Phi(\mathbf{x})$ |
| :--- | :--- |

Linear classifier in feature space

## Non-linear kernel learning

## Example of feature map



$$
\begin{aligned}
\mathbf{x} & =\left(x_{1}, x_{2}, x_{3}\right) \\
\Phi(\mathbf{x}) & =\left(1, x_{1}, x_{2}, x_{3}, x_{1} x_{2}, x_{1} x_{3}, x_{2} x_{3}\right)
\end{aligned}
$$

x is "lifted" to feature space

## Proposal for Learning

Grayscale image data

$$
\begin{aligned}
& 000000000000000 \\
& 11111111111111 \\
& 222222222222220 \\
& 333333333333333 \\
& 444444444444444 \\
& 555555555555555 \\
& 666666666666666 \\
& 777777777777771 \\
& 888888888888888 \\
& 999999999999999
\end{aligned}
$$

Map pixels to "spins"


Map pixels to "spins"


Map pixels to "spins"


## Local feature map, dimension $\mathrm{d}=2$

$$
\phi\left(x_{j}\right)=\left[\cos \left(\frac{\pi}{2} x_{j}\right), \sin \left(\frac{\pi}{2} x_{j}\right)\right] \quad x_{j} \in[0,1]
$$



Crucially, grayscale values not orthogonal

$$
\begin{aligned}
& \mathbf{x}=\text { input } \\
& \phi=\text { local feature map }
\end{aligned}
$$

## Total feature map $\Phi(\mathbf{x})$

$$
\Phi^{s_{1} s_{2} \cdots s_{N}}(\mathbf{x})=\phi^{s_{1}}\left(x_{1}\right) \otimes \phi^{s_{2}}\left(x_{2}\right) \otimes \cdots \otimes \phi^{s_{N}}\left(x_{N}\right)
$$

- Tensor product of local feature maps / vectors
- Just like product state wavefunction of spins
- Vector in $2^{N}$ dimensional space

$$
\begin{aligned}
& \mathbf{x}=\text { input } \\
& \phi=\text { local feature map }
\end{aligned}
$$

## Total feature map $\Phi(\mathbf{x})$

More detailed notation

$$
\left.\begin{array}{cc}
\mathbf{x}=\left[\begin{array}{llll}
x_{1}, & x_{2}, & x_{3}, & \ldots
\end{array}, x_{N}\right.
\end{array}\right] \quad \text { raw input }, ~\left(\begin{array}{l}
\phi_{1}\left(x_{1}\right) \\
\phi_{2}\left(x_{1}\right)
\end{array}\right] \otimes\left[\begin{array}{l}
\phi_{1}\left(x_{2}\right) \\
\phi_{2}\left(x_{2}\right)
\end{array}\right] \otimes\left[\begin{array}{l}
\phi_{1}\left(x_{3}\right) \\
\phi_{2}\left(x_{3}\right)
\end{array}\right] \otimes \cdots \otimes\left[\begin{array}{l}
\phi_{1}\left(x_{N}\right) \\
\phi_{2}\left(x_{N}\right)
\end{array}\right] \begin{aligned}
& \text { feature } \\
& \text { vector }
\end{aligned}
$$

```
x = input
\phi= local feature map
```


## Total feature map $\Phi(\mathbf{x})$

Tensor diagram notation

$$
\mathbf{x}=\left[\begin{array}{lllll}
x_{1}, & x_{2}, & x_{3}, & \ldots & x_{N}
\end{array}\right]
$$

raw inputs

$$
\because
$$

feature vector

## Construct decision function

$$
f(\mathbf{x})=W \cdot \Phi(\mathbf{x})
$$



## Construct decision function

$$
f(\mathbf{x})=W \cdot \Phi(\mathbf{x})
$$



## Construct decision function

$$
f(\mathbf{x})=W \cdot \Phi(\mathbf{x})
$$

$$
f(\mathbf{x})=\overparen{\bigcirc \bigcirc \bigcirc \bigcirc \bigcirc(x)}
$$

Construct decision function

$$
f(\mathbf{x})=W \cdot \Phi(\mathbf{x})
$$

$$
f(\mathbf{x})=\$ 1 \begin{aligned}
& W \\
& \Phi(\mathbf{x})
\end{aligned}
$$

## $W=\$$

Main approximation

$$
W=\overparen{T 1,11}
$$

## order- $N$ tensor



matrix product state (MPS)

MPS form of decision function

$$
f(x)=
$$

## Linear scaling

Can use algorithm similar to DMRG to optimize
$N=$ size of input
Scaling is $N \cdot N_{T} \cdot m^{3}$
$N_{T}=$ size of training set
$m=$ MPS bond dimension


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## Linear scaling

Can use algorithm similar to DMRG to optimize

$$
N=\text { size of input }
$$

Scaling is $N \cdot N_{T} \cdot m^{3}$

$N_{T}=$ size of training set<br>$m=$ MPS bond dimension



## Linear scaling

Can use algorithm similar to DMRG to optimize

$$
\begin{aligned}
N & =\text { size of input } \\
N_{T} & =\text { size of training set } \\
m & =\text { MPS bond dimension }
\end{aligned}
$$

Scaling is $N \cdot N_{T} \cdot m^{3}$


Could improve with stochastic gradient

Multi-class extension of model

## Decision function $f^{\ell}(\mathbf{x})=W^{\ell} \cdot \Phi(\mathbf{x})$

Index $\ell$ runs over possible labels

Predicted label is $\operatorname{argmax}_{\ell}\left|f^{\ell}(\mathbf{x})\right|$

## MNIST Experiment

MNIST is a benchmark data set of grayscale handwritten digits (labels $\ell=0,1,2, \ldots, 9$ )

60,000 labeled training images 10,000 labeled test images

$$
\begin{aligned}
& 000000000000000 \\
& 111111111111111 \\
& 222222222222220 \\
& 333333333333333 \\
& 444444444444444 \\
& 555555355555555 \\
& 666666666666666 \\
& 777777777777777 \\
& 888888888888888 \\
& 999999999999999
\end{aligned}
$$

## MNIST Experiment

One-dimensional mapping


MNIST Experiment

Results

| Bond dimension | Test Set Error |  |
| :---: | :---: | :---: |
| $m=10$ | $\sim 5 \%$ | $(500 / 10,000$ incorrect $)$ |
| $m=20$ | $\sim 2 \%$ | $(200 / 10,000$ incorrect) |
| $m=120$ | $0.97 \%$ | $(97 / 10,000$ incorrect $)$ |

State of the art is $<1 \%$ test set error

MNIST Experiment

## $\longrightarrow$ Demo

Link: http://itensor.org/miles/digit/index.html

## Understanding Tensor Network Models

$$
f(x)=
$$

Again assume $W$ is an MPS

$$
f(x)=
$$

Many interesting benefits
Two are:

1. Adaptive
2. Feature sharing
3. Tensor networks are adaptive

boundary pixels not useful for learning
$\underbrace{}_{\substack{\text { grayscale } \\ \text { training } \\ \text { data }}}$

$$
\begin{array}{llllllllll}
0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9
\end{array}
$$

2. Feature sharing



- Different central tensors
- "Wings" shared between models
- Regularizes models

2. Feature sharing


Progressively learn shared features

2. Feature sharing


Progressively learn shared features

2. Feature sharing


Progressively learn shared features
2. Feature sharing


Progressively learn shared features

## Deliver to central tensor



## Nature of Weight Tensor

Representer theorem says exact $W=\sum_{j} \alpha_{j} \Phi\left(x_{j}\right)$

Density plots of trained $W^{\ell}$ for each label $\ell=0,1, \ldots, 9$

## Nature of Weight Tensor

Representer theorem says exact $W=\sum_{j} \alpha_{j} \Phi\left(x_{j}\right)$

Tensor network approx. can violate this condition

$$
W_{\mathrm{MPS}} \neq \sum_{j} \alpha_{j} \Phi\left(x_{j}\right) \quad \text { for any } \quad\left\{\alpha_{j}\right\}
$$

- Tensor network learning not interpolation
- Interesting consequences for generalization?


## Some Future Directions

- Apply to 1D data sets (audio, time series)
- Other tensor networks: TTN, PEPS, MERA
- Useful to interpret $|W \cdot \Phi(\mathbf{x})|^{2}$ as probability? Could import even more physics insights.
- Features extracted by elements of tensor network?


## What functions realized for arbitrary $W$ ?

Instead of "spin" local feature map, use*

$$
\phi(x)=(1, x)
$$

Recall total feature map is

$$
\Phi(\mathbf{x})=\left[\begin{array}{l}
\phi_{1}\left(x_{1}\right) \\
\phi_{2}\left(x_{1}\right)
\end{array}\right] \otimes\left[\begin{array}{l}
\phi_{1}\left(x_{2}\right) \\
\phi_{2}\left(x_{2}\right)
\end{array}\right] \otimes\left[\begin{array}{l}
\phi_{1}\left(x_{3}\right) \\
\phi_{2}\left(x_{3}\right)
\end{array}\right] \otimes \cdots \otimes\left[\begin{array}{l}
\phi_{1}\left(x_{N}\right) \\
\phi_{2}\left(x_{N}\right)
\end{array}\right]
$$

$N=2$ case

$$
\phi(x)=(1, x)
$$

$$
\begin{aligned}
\Phi(\mathbf{x}) & =\left[\begin{array}{c}
1 \\
x_{1}
\end{array}\right] \otimes\left[\begin{array}{c}
1 \\
x_{2}
\end{array}\right] \\
& =\left(1, x_{1}, x_{2}, x_{1} x_{2}\right)
\end{aligned}
$$

$$
\begin{array}{r}
\left.f(\mathbf{x})=W \cdot \Phi(\mathbf{x})=\quad \cdot\left(1, \quad x_{11}, W_{21}, W_{12}, W_{22}\right), x_{1} x_{2}\right) \\
= \\
=W_{11}+W_{21} x_{1}+W_{12} x_{2}+W_{22} x_{1} x_{2}
\end{array}
$$

$\mathrm{N}=3$ case

$$
\phi(x)=(1, x)
$$

$$
\begin{aligned}
\Phi(\mathbf{x}) & =\left[\begin{array}{c}
1 \\
x_{1}
\end{array}\right] \otimes\left[\begin{array}{c}
1 \\
x_{2}
\end{array}\right] \otimes\left[\begin{array}{c}
1 \\
x_{3}
\end{array}\right] \\
& =\left(1, x_{1}, x_{2}, x_{3}, x_{1} x_{2}, x_{1} x_{3}, x_{2} x_{3}, x_{1} x_{2} x_{3}\right) \\
f(\mathbf{x}) & =W \cdot \Phi(\mathbf{x}) \\
& =W_{111}+W_{211} x_{1}+W_{121} x_{2}+W_{112} x_{3} \\
& +W_{221} x_{1} x_{2}+W_{212} x_{1} x_{3}+W_{122} x_{1} x_{3} \\
& +W_{222} x_{1} x_{2} x_{3}
\end{aligned}
$$

## General $N$ case

$$
\begin{aligned}
f(\mathbf{x})= & W \cdot \Phi(\mathbf{x}) & & \\
= & W_{111 \cdots 1} & & \text { constan } \\
& +W_{211 \cdots 1} x_{1}+W_{121 \cdots 1} x_{2}+W_{112 \cdots 1} x_{3}+\ldots & & \text { singles } \\
& +W_{221 \cdots 1} x_{1} x_{2}+W_{212 \cdots 1} x_{1} x_{3}+\ldots & & \text { doubles } \\
& +W_{222 \cdots 1} x_{1} x_{2} x_{3}+\ldots & & \text { triples } \\
& +\ldots & & \\
& +W_{222 \cdots 2} x_{1} x_{2} x_{3} \cdots x_{N} & & N \text {-tuple }
\end{aligned}
$$

constant
singles
doubles
triples

N-tuple

Model has exponentially many formal parameters

## Related Work

## Novikov, Trofimov, Oseledets (1605.03795)

- matrix product states + kernel learning
- stochastic gradient descent

Cohen, Sharir, Shashua (1410.0781, 1506.03059, 1603.00162, 1610.04167)

- tree tensor networks
- expressivity of tensor network models
- correlations of data (analogue of entanglement entropy)
- generative proposal


## Other MPS related work ( = "tensor trains")

Markov random field models
Novikov et al., Proceedings of 31st ICML (2014)

Large scale PCA
Lee, Cichocki, arxiv: 1410.6895 (2014)

Feature extraction of tensor data
Bengua et al., IEEE Congress on Big Data (2015)

Compressing weights of neural nets
Novikov et al., Advances in Neural Information Processing (2015)

